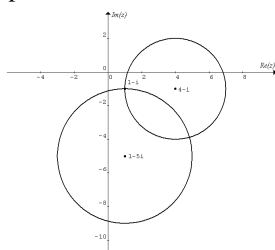


Section 1

1	2	3	4	5	6	7	8	9	10	11
A	C	E	D	E	E	A	E	C	A	B

12	13	14	15	16	17	18	19	20	21	22
D	B	B	B	B	A	C	C	B	D	E

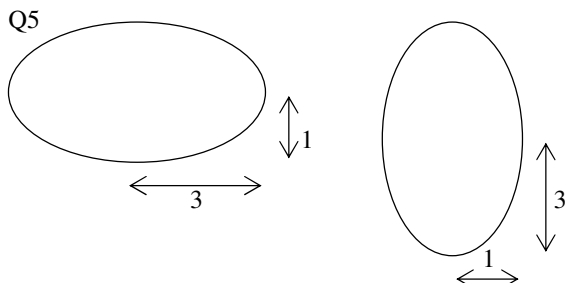
Q1 A possible complex number is $z = 1 - i$, $|z| = \sqrt{2}$ A



Q2 $z = -icis(2)$ is the clockwise rotation of $cis(2)$ about the origin O by $\frac{\pi}{2}$. $\therefore Arg(z) = 2 - \frac{\pi}{2}$ C

Q3 Let $z = x + yi$.
 $az^2 + b|z|^2 - c = 0$, $a(x^2 - y^2 + 2xyi) + b(x^2 + y^2) - c = 0$
 $\therefore [(a+b)x^2 + (b-a)y^2 - c] + 2axyi = 0$
 $\therefore (a+b)x^2 + (b-a)y^2 - c = 0$ and $xy = 0$
 \therefore either $x = 0$ and $y = \pm \sqrt{\frac{c}{b-a}}$ if $b > a$
 or $y = 0$ and $x = \pm \sqrt{\frac{c}{b+a}}$

Q4 $0 < Arg[(1+i)z] < \frac{\pi}{2}$, $0 < Arg(1+i) + Arg(z) < \frac{\pi}{2}$,
 $0 < \frac{\pi}{4} + Arg(z) < \frac{\pi}{2}$, $-\frac{\pi}{4} < Arg(z) < \frac{\pi}{4}$



Q5 $\frac{(x-h)^2}{9} + (y-k)^2 = 1$ or $(x-h)^2 + \frac{(y-k)^2}{9} = 1$ E

Q6 $y = \frac{1}{a+bx+ax^2}$ has a vertical and a horizontal asymptotes when $a+bx+ax^2$ is a perfect square, i.e. $\Delta = b^2 - 4a^2 = 0$
 $\therefore \frac{a}{b} = \pm \frac{1}{2}$ E

Q7 Asymptotes: $y = 2 \pm \left(\frac{1}{2}x + 1\right)$, $y - 2 = \pm \frac{1}{2}(x + 2)$
 \therefore the two asymptotes intersect at $(-2, 2)$ which is the centre of the hyperbola, also $\frac{b}{a} = \frac{1}{2}$.

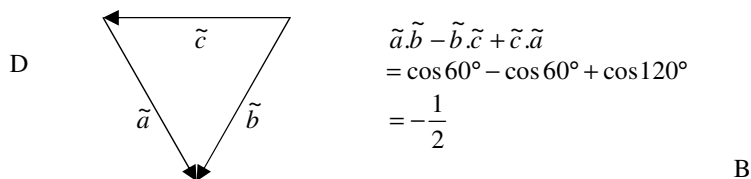
A possible equation of the hyperbola is $\frac{(x+2)^2}{2^2} - \frac{(y-2)^2}{1^2} = 1$,
 i.e. $(x+2)^2 - 4(y-2)^2 - 4 = 0$ A

Q8 $\sec(a) + \operatorname{cosec}(b) = 0$, $\sec(a) = -\operatorname{cosec}(b)$
 $\therefore \cos(a) = -\sin(b)$, $\cos(a) = -\cos\left(\frac{\pi}{2} - b\right)$
 Since $\pi < a < \frac{3\pi}{2}$ and $0 < b < \frac{\pi}{2}$, $\therefore a = \pi + \left(\frac{\pi}{2} - b\right) = \frac{3\pi}{2} - b$
 $\therefore a + b = \frac{3\pi}{2}$ E

Q9 The domain of the inverse of f is the range of f .
 As $x \rightarrow 1^+$, $y \rightarrow \sec \pi + a\pi = a\pi - 1$
 At $x = \frac{5}{3}$, $y = \sec \frac{4\pi}{3} + a\pi = a\pi - 2$
 \therefore the domain of the inverse of f is $[a\pi - 2, a\pi - 1)$. C

Q10 $\tan^{-1}(x-a+b) - \tan^{-1}(x-a) = \pi$
 $\tan^{-1}(x-a+b)$ and $\tan^{-1}(x-a)$ have the same range
 $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$, $\therefore \tan^{-1}(x-a+b) - \tan^{-1}(x-a) \neq \pi$ for $x \in R$ A

Q11 Since $\tilde{a} - \tilde{b} + \tilde{c} = \tilde{0}$, \therefore unit vectors \tilde{a} , \tilde{b} and \tilde{c} form an equilateral triangle as shown below:



Q12 Let $\tilde{j} + c\tilde{k} = m(\tilde{k} + a\tilde{i}) + n(\tilde{i} + b\tilde{j})$ where m and n are non-zero real numbers.
 $\tilde{j} + c\tilde{k} = (ma+n)\tilde{i} + nb\tilde{j} + m\tilde{k}$
 $\therefore ma+n=0$, $nb=1$ and $m=c$
 $\therefore ca+n=0$, $n=-ca$
 $\therefore abc = -1$ D

Q13 $\tilde{p} = \pm(\tilde{i} + \tilde{j} + \tilde{k})$ are vectors which make equal angle θ with each of the orthogonal unit vectors \tilde{i} , \tilde{j} and \tilde{k} .
 $\cos \theta = \pm \frac{1}{\sqrt{1+1+1}}$, $\therefore \theta \approx 55^\circ$ and 125° B

Q14 Given $f(0)=1.2$, by CAS $f(0.2)=\int_0^{0.2} \frac{1}{\cos^4 x} dx + 1.2 \approx 1.4$,

$f(0.4)=\int_0^{0.4} \frac{1}{\cos^4 x} dx + 1.2 \approx 1.6$, $f(0.6)=\int_0^{0.6} \frac{1}{\cos^4 x} dx + 1.2 \approx 2$

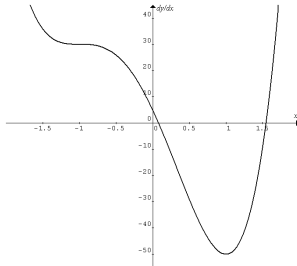
$f(0.8)=\int_0^{0.8} \frac{1}{\cos^4 x} dx + 1.2 \approx 2.6$, $f(1)=\int_0^1 \frac{1}{\cos^4 x} dx + 1.2 \approx 4$

Average value $\approx \frac{1.2+1.4+1.6+2+2.6+4}{6} \approx 2$ B

Q15 At a point of inflection the gradient of the curve is a local maximum/minimum.

$y = 3x^5 + 5x^4 - 10x^3 - 30x^2 + 5x - 10$

$\frac{dy}{dx} = 15x^4 + 20x^3 - 30x^2 - 60x + 5$



$\frac{dy}{dx}$ has a local minimum at $x = 1$. B

Q16 When $y = 2$ and $0 \leq x \leq \frac{3}{2}$, $\tan^2 x = 4$, $x \approx 1.10715$

By CAS, $\int_0^{1.10715} \tan^2 x dx \approx 0.8929$

Area of the required region $\approx 4 \times 1.10715 - 0.8929 \approx 3.5$ B

Q17 The quadratic equation has exactly one solution, $\therefore \Delta = 0$

$k^2 - 4(1)(1) = 0$, $\therefore k = 2$

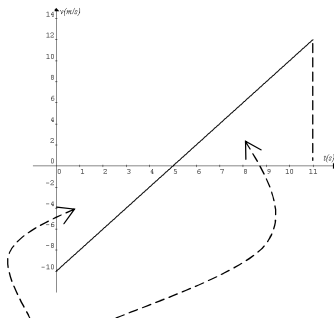
$\left(\frac{dy}{dx} + 1\right)^2 = 0$, $\therefore \frac{dy}{dx} = -1$, $y = -x + c$

$(1,1)$, $\therefore c = 2$, $\therefore x + y = 2$

Q18 $a = 2$, $u = 10$, $s = 16 - 5 = 11$, $v?$

$v^2 = u^2 + 2as$, $v = 12$

$v = 2t - 10$



Total distance $= 25 + 36 = 61$ m B

Q19 Given $v = 2 - e^x$, when $a = v \frac{dv}{dx} = (2 - e^x)(-e^x) = 0$, $e^x = 2$, $x = \log_e 2$ and $v = 0$. \therefore the particle is moving in the same direction from $x = 0$ to $x = \log_e 2$.

Distance $= \log_e 2 \approx 0.7$ m C

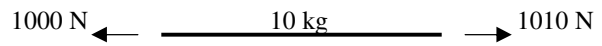
Q20 $a = 9.8 \sin 30^\circ = 4.9$, $s = 1.3$, $u = 0$, $v?$

$v^2 = u^2 + 2as$, $v \approx 3.57$

Momentum $= mv \approx 1.3 \times 3.57 \approx 4.6$ kg m s⁻¹ B

Q21 The particle exerts a downward force on the inclined plane equal in magnitude to the weight of the particle, \therefore the upward reaction force of the inclined plane on the particle is also equal in magnitude to the weight of the particle according to Newton's third law, $mg = 2.04 \times 9.8 \approx 20$ N upward D

Q22 Acceleration of the crate = acceleration of the chain
Consider the forces on the chain:



$a = \frac{R}{m} = \frac{1010 - 1000}{10} = 1$ m s⁻² E

Section 2

Q1a $x^2 + 4y^2 = 4 \xrightarrow{(1)} x^2 + 4\left(y - \frac{1}{2}\right)^2 = 4$

$\xrightarrow{(2)} x^2 + 4\left(\frac{1}{2}y - \frac{1}{2}\right)^2 = 4$, and in simplified form

$x^2 + (y - 1)^2 = 4$.

Q1b Let $y = 0$, $x^2 = 3$, $x = \pm\sqrt{3}$

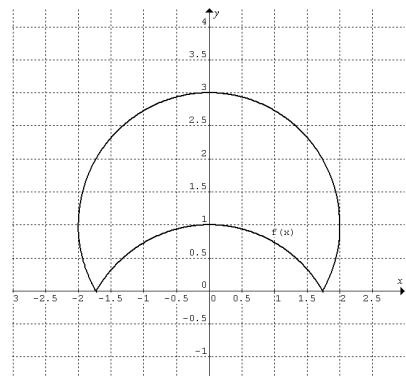
The x -intercepts are $(-\sqrt{3}, 0)$ and $(\sqrt{3}, 0)$.

A Q1ci $x^2 + (y - 1)^2 = 4$, $(y - 1)^2 = 4 - x^2$, $y - 1 = \pm\sqrt{4 - x^2}$

$\therefore g(x) = 1 - \sqrt{4 - x^2}$,

$\therefore f(x) = |g(x)| = \sqrt{4 - x^2} - 1$ for $-\sqrt{3} < x < \sqrt{3}$

Q1cii



Q1d Volume V_1 of solid by formed by rotating $f(x)$:

$$y = \sqrt{4-x^2} - 1, \sqrt{4-x^2} = y+1, x^2 = 4-(y+1)^2$$

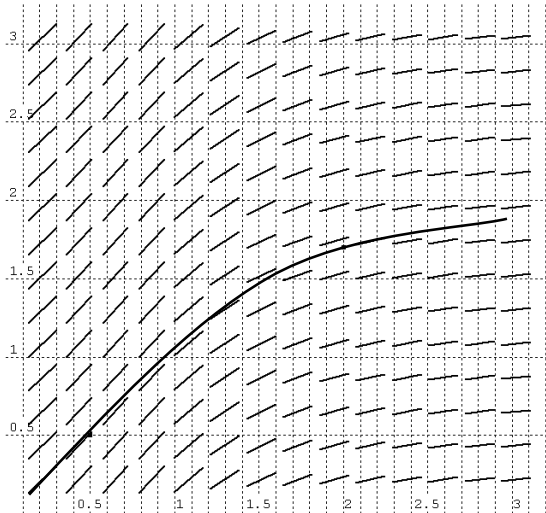
$$V_1 = \int_0^1 \pi x^2 dy = \pi \int_0^1 (4-(y+1)^2) dy = \frac{5\pi}{3}$$

$$\text{Volume of the large sphere } V_2 = \frac{4}{3} \pi (2^3) = \frac{32\pi}{3}$$

\therefore Volume of revolution of the required region

$$= \frac{32\pi}{3} - 2 \times \frac{5\pi}{3} = \frac{22\pi}{3}$$

Q2a



When $x = 2$, $y \approx 1.7$

Q2b

$$x = 0.5 \quad y = 0.5$$

$$\frac{dy}{dx} \approx 1.1765$$

$$x = 1.0 \quad y = 0.5 + 0.5 \times 1.1765 \approx 1.0882$$

$$\frac{dy}{dx} = 1$$

$$x = 1.5 \quad y = 1.0882 + 0.5 \times 1 \approx 1.5882$$

$$\frac{dy}{dx} \approx 0.5361$$

$$x = 2.0 \quad y \approx 1.5882 + 0.5 \times 0.5361 \approx 1.9$$

$$\text{Q2c } y = \int_{0.5}^2 \frac{1+x^2}{1+x^4} dx + 0.5 \approx 1.7 \text{ by CAS}$$

$$\text{Q2di } \frac{\frac{1+x^2}{x^2}}{\frac{1+x^4}{x^2}} = \frac{\frac{1}{x^2} + 1}{\frac{1}{x^2} + x^2}$$

$$\text{Q2dii } x^2 + \frac{1}{x^2} = \left(x + \frac{b}{x}\right)^2 + c = x^2 + 2b + \frac{b^2}{x^2} + c,$$

$$\therefore b^2 = 1, 2b + c = 0 \text{ and } c > 0$$

$$\therefore b = -1 \text{ and } c = 2$$

$$\therefore x^2 + \frac{1}{x^2} = \left(x - \frac{1}{x}\right)^2 + 2$$

$$\text{Q2diii } y = \int \frac{1+x^2}{1+x^4} dx = \int \frac{\frac{1}{x^2} + 1}{\left(x - \frac{1}{x}\right)^2 + 2} dx$$

$$= \int \frac{\frac{du}{dx}}{u^2 + 2} dx = \int \frac{1}{2+u^2} du$$

$$= \frac{1}{\sqrt{2}} \tan^{-1}\left(\frac{u}{\sqrt{2}}\right) + c$$

$$= \frac{1}{\sqrt{2}} \tan^{-1}\left(\frac{1}{\sqrt{2}}\left(x - \frac{1}{x}\right)\right) + c$$

$$\text{Let } u = x - \frac{1}{x}$$

$$\frac{du}{dx} = 1 + \frac{1}{x^2}$$

Q2div When $x = 0.5$, $y = 0.5$

$$0.5 = \frac{1}{\sqrt{2}} \tan^{-1}\left(\frac{1}{\sqrt{2}}\left(0.5 - \frac{1}{0.5}\right)\right) + c, \quad c = 1.0762$$

$$\therefore y = \frac{1}{\sqrt{2}} \tan^{-1}\left(\frac{1}{\sqrt{2}}\left(x - \frac{1}{x}\right)\right) + 1.0762$$

When $x = 2$, $y \approx 1.7$

$$\text{Q3a } \vec{P_1P_2} = \tilde{b} - \tilde{a}, \quad |\vec{P_1P_2}|^2 = \vec{P_1P_2} \cdot \vec{P_1P_2} = (\tilde{b} - \tilde{a}) \cdot (\tilde{b} - \tilde{a})$$

$$= \tilde{a} \cdot \tilde{a} + \tilde{b} \cdot \tilde{b} - 2\tilde{a} \cdot \tilde{b} = |\tilde{a}|^2 + |\tilde{b}|^2 - 2|\tilde{a}||\tilde{b}|\cos\alpha$$

Q3b Since the length of arc P_1P_2 equals the length of arc P_2P_3 ,

$$\therefore \angle P_2OP_3 = \angle P_1OP_2 = \alpha$$

$$|\vec{P_2P_3}|^2 = |\tilde{b}|^2 + |\tilde{c}|^2 - 2|\tilde{b}||\tilde{c}|\cos\alpha$$

Q3c Since the length of arc P_1P_2 equals the length of arc P_2P_3 ,

$$\therefore |\vec{P_1P_2}|^2 = |\vec{P_2P_3}|^2$$

$$\therefore |\tilde{a}|^2 + |\tilde{b}|^2 - 2|\tilde{a}||\tilde{b}|\cos\alpha = |\tilde{b}|^2 + |\tilde{c}|^2 - 2|\tilde{b}||\tilde{c}|\cos\alpha$$

$$\therefore |\tilde{a}|^2 - |\tilde{c}|^2 = 2|\tilde{b}||\tilde{a} - \tilde{c}|\cos\alpha$$

$$\therefore \cos\alpha = \frac{|\tilde{a}|^2 - |\tilde{c}|^2}{2|\tilde{b}||\tilde{a} - \tilde{c}|} = \frac{|\tilde{a}| + |\tilde{c}|}{2|\tilde{b}|}$$

Q3d Since OP_1 is a diameter, $\therefore \angle OP_2P_1$ and $\angle OP_3P_1$ are right angles.

$\therefore \tilde{b}$ is the vector resolute of \tilde{a} in the direction of $\vec{OP_2}$ and \tilde{c}

is the vector resolute of \tilde{a} in the direction of $\vec{OP_3}$.

Q3e Given the length of $\vec{OP_1} = |\tilde{a}| = 1$, $\therefore |\tilde{b}| = 1 \cos\alpha = \cos\alpha$

and $|\tilde{c}| = 1 \cos 2\alpha = \cos 2\alpha$.

$$\text{Q3f } \cos\alpha = \frac{|\tilde{a}| + |\tilde{c}|}{2|\tilde{b}|}, \quad \cos\alpha = \frac{1 + \cos 2\alpha}{2 \cos\alpha}, \quad \therefore 1 + \cos 2\alpha = 2 \cos^2 \alpha$$

$$\text{Q3g } \cos\alpha = \frac{|\tilde{b}| + |\tilde{d}|}{2|\tilde{c}|} \text{ and } |\tilde{d}| = \cos 3\alpha \text{ by similar methods,}$$

$$\therefore \cos\alpha = \frac{\cos\alpha + \cos 3\alpha}{2 \cos 2\alpha},$$

$$\therefore \cos\alpha + \cos 3\alpha = 2 \cos\alpha \cos 2\alpha$$

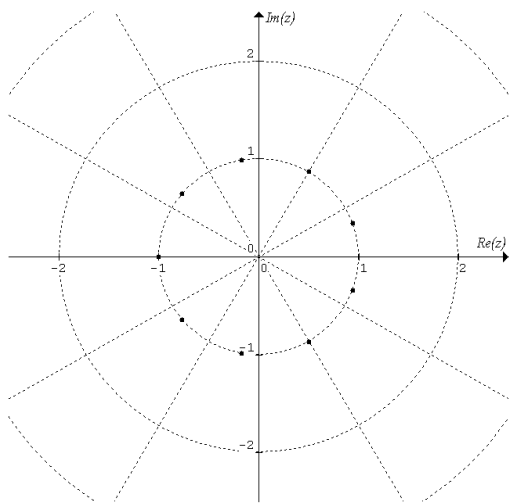
$$\text{Q4a } \frac{z^9+1}{z^6-z^3+1} = \frac{z^9+0z^6+0z^3+1}{z^6-z^3+1}$$

$$\frac{z^3+1}{z^6-z^3+1} \frac{z^3+1}{z^3+1} = \frac{z^6-z^3+1}{z^6-z^3+1} - \frac{(z^9-z^6+z^3)}{z^6-z^3+1}$$

$$\frac{z^6-z^3+1}{z^6-z^3+1} - \frac{(z^9-z^6+z^3)}{z^6-z^3+1} = 0$$

$$\therefore \frac{z^9+1}{z^6-z^3+1} = z^3+1$$

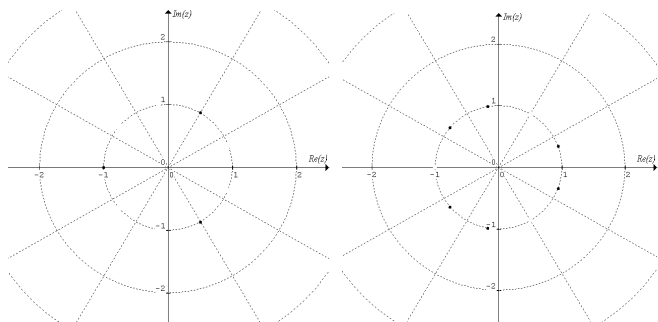
Q4b $z^9+1=0$ has a real root $z=-1$, together with the other 8 roots they space out equally on the unit circle.



$$\text{Q4c } \frac{2\pi}{9}$$

$$\text{Q4di } z^9+1 = (z^3+1)(z^6-z^3+1) = (z^3+1)P_2(z) = 0$$

The roots of $z^3+1=0$ (left) and the roots of $P_2(z)=0$ (right) are shown below:



The roots of $P_2(z)=0$ are:

$$z = cis\left(\pm \frac{\pi}{9}\right), z = cis\left(\pm \frac{5\pi}{9}\right) \text{ and } z = cis\left(\pm \frac{7\pi}{9}\right).$$

Q4dii The roots of $P_2(iz)=0$ are:

$$iz = cis\left(\pm \frac{\pi}{9}\right), z = \frac{cis\left(\pm \frac{\pi}{9}\right)}{i} = \frac{cis\left(\pm \frac{\pi}{9}\right)}{cis\left(\frac{\pi}{2}\right)} = cis\left(-\frac{7\pi}{18}\right) \text{ or } cis\left(-\frac{11\pi}{18}\right)$$

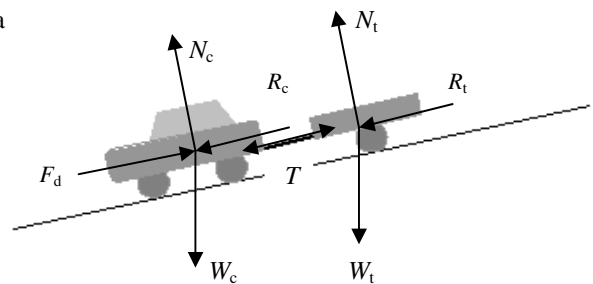
$$iz = cis\left(\pm \frac{5\pi}{9}\right), z = cis\left(\frac{\pi}{18}\right) \text{ or } cis\left(\frac{17\pi}{18}\right)$$

$$iz = cis\left(\pm \frac{7\pi}{9}\right), z = cis\left(\frac{5\pi}{18}\right) \text{ or } cis\left(\frac{13\pi}{18}\right)$$

$$\text{Q4e } cis\left(-\frac{7\pi}{18}\right) cis\left(-\frac{11\pi}{18}\right) cis\left(\frac{\pi}{18}\right) cis\left(\frac{17\pi}{18}\right) cis\left(\frac{5\pi}{18}\right) cis\left(\frac{13\pi}{18}\right)$$

$$= cis\left(-\frac{7\pi}{18} - \frac{11\pi}{18} + \frac{\pi}{18} + \frac{17\pi}{18} + \frac{5\pi}{18} + \frac{13\pi}{18}\right) = cis(\pi) = -1$$

Q5a



$$\text{Q5b } \text{Mass of the car} = \frac{15000}{9.8} \text{ kg; mass of the trailer} = \frac{5000}{9.8} \text{ kg}$$

$$\text{At } t=0, a = 0.8 \cos^2 0 = 0.8$$

Apply Newton's second law to the car and the trailer: $R = ma$,

$$F_d - 300 - 200 - 15000 \sin 20^\circ - 5000 \sin 20^\circ = \frac{15000+5000}{9.8} \times 0.8$$

$$\therefore F_d \approx 9.0 \times 10^3 \text{ N}$$

Q5c Apply Newton's second law to the trailer:

$$T - 200 - 5000 \sin 20^\circ = \frac{5000}{9.8} \times 0.8, T \approx 2.3 \times 10^3 \text{ N}$$

Q5d The car and the trailer accelerate for the first 2 s:

$$\Delta v = \int_0^2 0.8 \cos^2\left(\frac{\pi}{4}\right) dt = 0.8; \text{ there is no change in the velocity}$$

in the next second.

The car and the trailer start from rest,

$$\therefore \text{the exact speed of the trailer after the first 3 s is } 0.8 \text{ m s}^{-1}.$$

$$\text{Q5e } \text{Distance} = 0.8(8-3) = 4 \text{ m.}$$

Please inform mathline@itute.com re conceptual, mathematical and/or typing errors